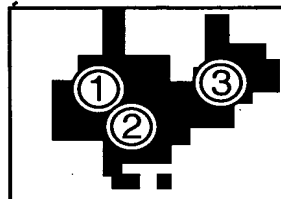
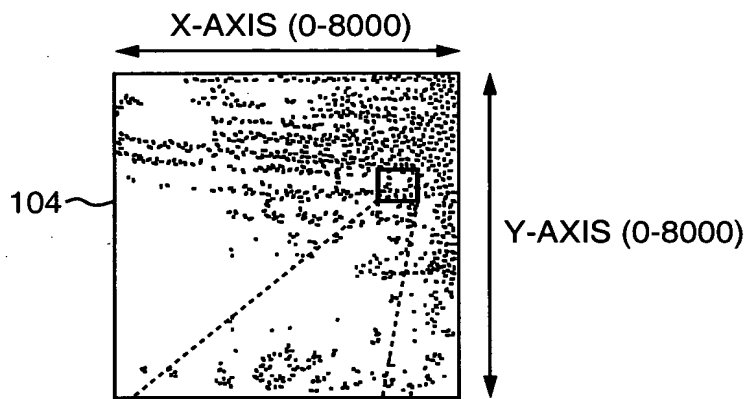


FIG. 3A



ROBOT COORDINATES "CLICK-ON-A-SPOT"	
1	x=630, y=248
2	x=640, y=260
3	x=700, y=240

FIG. 3B

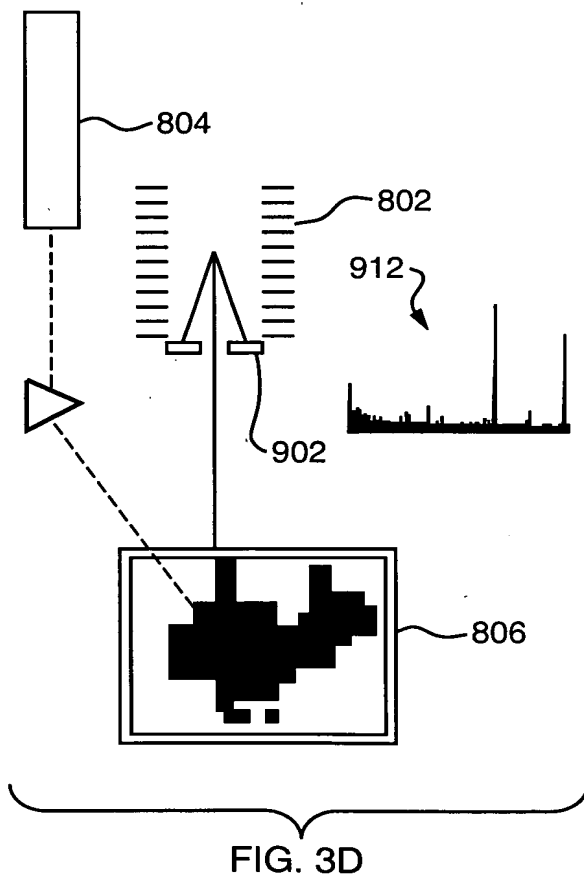


FIG. 3D

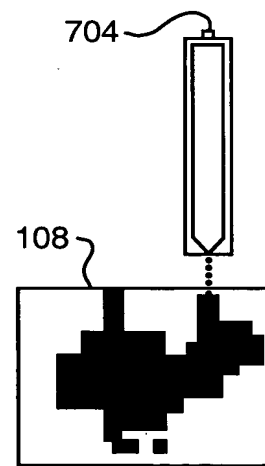


FIG. 3C